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An acoustic sensor transmitter for in situ assessment of water quality and fish behaviour during chemical treatment of a parasite-infected river system: tag design and practical use

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Abstract

Background: Behaviour of potential host fish during chemical treatment against the ectoparasite *Gyrodactylus salaris* is a vital factor in designing treatment strategies, evaluating risk factors and establishing insights into previously failed treatments. The effectiveness of any chemical treatment may be compromised if fish either are forced to, or seek out actively, areas of the river where the water quality is less affected by the chemicals. The aim of this study was to develop and apply an acoustic fish tag for fish localization with sensors for in situ measurement of water conductivity and temperature to investigate fish behaviour before, during and after an aluminium (Al) treatment. The sensor tag allowed discrimination between water qualities, and thereby quantification of exposure to treatment water.

Findings: Adult Atlantic salmon and anadromous brown trout from river Lærdalselva were tagged with external conductivity transmitters and followed daily by a network of passive receivers and by manual tracking 1 week ahead of treatment, during a 2-week aluminium (Al) treatment period and one week after an Al treatment. The results show no avoidance behaviour related to the Al treatment and most of the fish exhibited a behaviour during the treatment that did not differ significantly from the behaviour observed before or after the treatment. Data collected from the tags showed that the fish experienced increased conductivity during Al administration, suggesting successful exposure to treatment water. The tag gave verifiable environmental information and functioned well in the turbulent and acoustically demanding river environment, albeit with variable detection range.

Conclusions: The conductivity and temperature tag provided novel data on fish behaviour and exposure during the Al treatment period. Results show that fish exhibit normal behaviour during this period and no avoidance response can be detected in the collected data.

Keywords: Acoustic telemetry, Conductivity, Salmonids, Aluminium, Water quality, CondTag, Parasite, *Gyrodactylus salaris*, Atlantic salmon, Anadromous brown trout

Background

In Norway, introduction and secondary dispersion of the monogenean parasite *Gyrodactylus salaris* has caused severe population decline of Atlantic salmon (*Salmo salar*) in infected rivers [1, 2]. The discovery of successful

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elimination of *G. salaris* infections in salmon by exposure to aqueous labile inorganic aluminium (Al_i) [3] has led to a scientific [4] and practical [5–7] efforts to develop a full-scale chemical treatment method for parasite elimination while maintaining fish populations in infected river systems. The eliminating effect on *G. salaris* of labile/cationic Al in acidified waters was first described by Soleng et al. [3] and the extensive knowledge of biological effects of Al, including dose–response relationships for host species Atlantic salmon and brown trout in the acidification literature [8] defined treatment conditions (Al, pH). The method involves administering of Al as aluminium sulphate and acid (H_2SO_4) for pH control (target pH: 5.9–5.7) to obtain a desired concentration of Al_i between 25–30 and $\mu g/l$. While the causative agent responsible for *G. salaris* removal from the host fish is cationic/labile Al, adding aluminium sulphate and additional sulfuric acid to decrease pH also results in a marked water conductivity increase in the river during treatment [9]. Thus, the increase in water conductivity caused by the addition of ions and lowering of pH serves as a practical proxy for measuring dose in situ. At present little is known about the spatio-temporal response pattern of fish to the water quality changes during an Al treatment period. Both experimental and field studies have demonstrated that Atlantic salmon is able to sense and avoid low pH [10] and in some cases also elevated concentrations of aluminium [11]. In other cases no avoidance has been observed for aluminium in Atlantic salmon both in the laboratory [12] and for a combined low pH/increased aluminium in a field study [13].

Fish behaviour during chemical treatment against *G. salaris* is a vital factor in designing treatment strategies, evaluating risk factors and establishing insights into previously failed treatments. The effectiveness of any chemical treatment may be compromised if fish either are forced to, or seek out actively, areas of the river where the water quality is less affected. Areas of brackish water and groundwater runoff are regarded as typical problem areas in this respect. Avoidance and escape reactions from elevated Al concentrations have been observed previously [14].

The aim of this study was to develop and apply an acoustic fish tag, with sensors capable of simultaneously measuring temperature and conductivity of the surrounding water to investigate to what extent avoidance behaviour occur before, during and after an Al treatment. The tag was used to track Atlantic salmon (*Salmo salar*) and anadromous brown trout (*Salmo trutta*) during the Al treatment of river Lærdalselva from August to September 2009. During this period the fish are on their spawning run in the river and moves from the estuary to their spawning sites [15]. For salmon and the mature

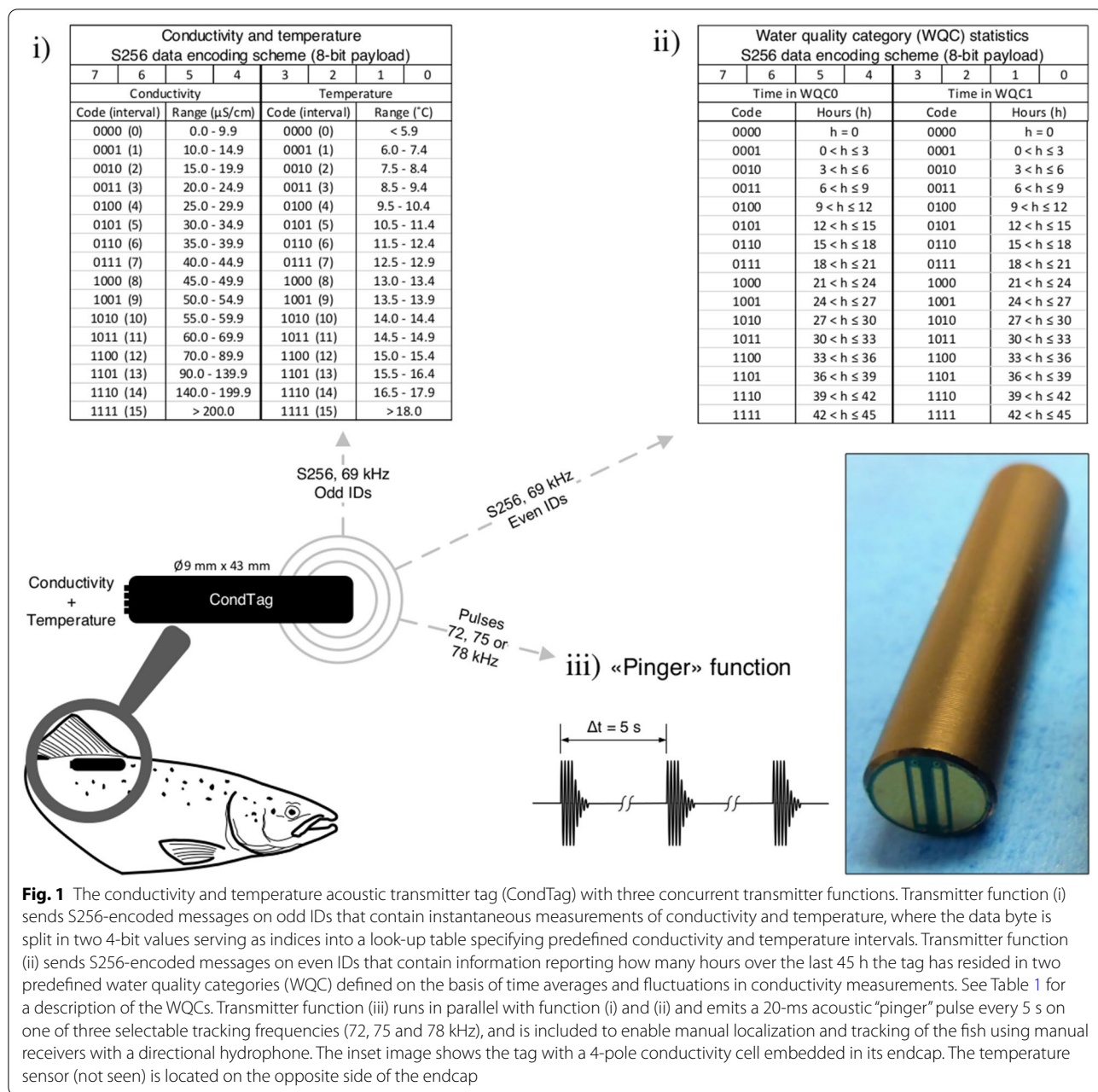
sea trout, both an upriver migration and more stable holding behaviour would be expected [16]. For smaller non-mature sea trout, one could expect both down and upstream migration. The reach of the river studied is the main spawning area of the river, and the fish will mostly spawn in the mainstem. Based on the measured variables, the sensor tag allows for discrimination between water qualities such as ground water, brackish water, chemically treated water and the normal river water. For example, the groundwater runoff to the river Lærdalselva sustains conductivity typically more than ten times that of river water (12–20 vs 150–350 $\mu S cm^{-1}$). When attached to fish, these transmitters can therefore be used to identify areas in the river and estuary used by fish where the chemical treatment for *G. salaris* might be suboptimal. Tracking fish before, during and after the treatment also gives indication of the exposure to the chemical reagent in the water and contributes to knowledge on behaviour during the treatment.

The study provides an example and ideas of how experimental objectives may be accommodated within the capabilities and limitations of contemporary digital tag platforms. Detailed field observations showing the dynamics of the fish's exposure to the chemical reagent under the circumstances of a full-scale treatment scenario are given as well as documentation of no avoidance behaviour both during and after treatment.

Methods

Transmitter design

An acoustic transmitter tag with a water conductivity and temperature sensor was developed specifically for this study to enable observations of individual behaviour and to quantify the exposure of fish to different water qualities during a chemical treatment. The tag was based on an ultra-low power mixed-signal electronic design similar to the acoustic tag platform described in Føre et al. [17], which allows physical miniaturization while securing long operational life and flexibility with respect to sensor integration, on-board data processing and storage capacity. To sense water conductivity, the tag incorporated a 4-pole gold-plated conductivity cell embedded in one of its end caps (Fig. 1) where the cell constant was dimensioned according to the conductivity range typical for the water in the river and estuary. Conductivity measurements were initiated and supervised by the on-board microcontroller and involved activation of a driver circuit that applied an alternating voltage of constant level to the outer pair of electrodes, while simultaneously sensing the corresponding voltage potential between the inner pair of electrodes and the total electrical current flowing through the water. The microcontroller measured the current and voltage signal for each cycle



by employing a micropower instrumentation amplifier and its integrated AD. Conductivity was calculated as an average over several cycles of the product of the cell constant and the ratio between the measured current and voltage. A calibrated NTC thermistor was embedded in the tag’s end cap adjacent to the electrodes and was used to sense ambient water temperature as well as compensating conductivity measurements for temperature dependency. The conductivity and temperature sensors were calibrated with selectable gain and offset settings to accommodate measurement ranges that were considered

suitable for the anticipated conditions at the study site. Although the conductivity sensor allowed a maximum measurement range of 0–2530 µScm⁻¹, the sensor was set to saturate at 200 µScm⁻¹ since the conductivity levels of both normal river water and treatment water were predicted to be very low. This gave a measurement resolution of 0.2 µScm⁻¹ and laboratory tests proved that accuracy was better than 1.4 µScm⁻¹ for these water types. The temperature sensor had a measurement range of – 2.0 to 25.5 °C with resolution 0.03 °C and accuracy better than 0.3 °C.

Both continuous and more sporadic observations of the fish were anticipated in the relatively long and varied river system. For this reason, the tag was designed and programmed as a multi-function transmitter in order to serve three different monitoring objectives simultaneously:

- (i) Transmit periodic measurements of instantaneous electrical conductivity and temperature of the tagged fish's ambient water.
- (ii) Calculate and transmit statistical information pertaining to the tagged fish's exposure to different water qualities over a defined time history.
- (iii) Emit regular and frequent "pings" to permit manual acoustic bearing measurements and localization of the tagged fish using one of three separate tracking frequencies.

In addition to manual tracking receivers, automatic monitoring receivers were used extensively for reception of the telemetry data (Vemco VR100 and VR2W, Halifax, NS, Canada). This implied that transmitter function (i) and (ii) had to be based on an acoustic carrier frequency of 69 kHz and the S256 encoding of acoustic messages [18]. The S256 encoding scheme only permits a 16-bit data payload for each message, which is equally divided between an 8-bit tag ID code and an 8-bit sensor data value. Each transmitter tag was therefore allocated two unique and consecutive ID codes, with odd and even ID codes representing transmitter function (i) and (ii), respectively, with transmission alternating and repeating at random intervals of 40–120 s. On-board compression techniques in terms of look-up tables and calculation of statistical moments were implemented in the tag firmware to convey useful sensor data within the limitation of one byte per transmission. Transmitter function (iii), the acoustic ping, was designed to operate concurrently with function (i) and (ii), but at separate frequencies to avoid acoustic interference with messages transmitted on the 69 kHz channel. The tag was thus programmed to emit short "ping pulses" of 20 ms duration every 5 s at either 72, 75 or 78 kHz (depending on the tag ID), which thereby permitted concurrent tracking of up to three co-located fish in the same stretch of the river while still being able to receive instantaneous and statistical data on conductivity and temperature.

Transmitter function (i) was implemented to provide instantaneous conductivity and temperature readings from the fish's ambient water as S256-encoded messages. This way data could be received at regular intervals using both automatic monitoring receivers (VR2W) that were permanently deployed in specific pools of the river as well as manual receivers (VR100) that were in ambulatory use during tracking campaigns. Due to the limited

one-byte data payload that can be sent during each transmission, conductivity and temperature sensor measurements were compressed into two 4-bit binary codes by a software algorithm that ran locally onboard the tag (see Fig. 1). These codes served as indices into two look-up tables containing predefined conductivity and temperature intervals. The approach employed data binning of each variable into one of 16 different intervals with a nonlinear mapping between bin number and interval size. While having rather low resolution, the mapping technique allowed enhanced resolution in the parts of the sensors' measurement ranges considered likely to prevail during the experiment, at the expense of lower resolution in ranges that were considered less likely to occur. The selection of intervals was done based on a priori knowledge of typical conductivity and temperature ranges of normal river water during the relevant season, as well as values representative of the water quality during AI treatment, of groundwater effluences, and of the river estuary. Details of the coding scheme of conductivity and temperature intervals are given in Fig. 1.

Transmitter function (ii) was implemented to provide statistical records of the fish's exposure to different water qualities over a specified temporal horizon. With tagged fish moving between locations in the complex and acoustically challenging habitat of the river, it was expected that signals would be beyond detection range of unknown extents of time during the experiment. Still, it was regarded as important to be able to reconstruct historical information concerning the fish's exposure to different water qualities once the fish again could be detected. All remaining data memory on-board the tag was thus allocated to a sliding time window data buffer, and an algorithm was developed to keep record of the fish time of exposure to three different water quality categories (WQC0, WQC1 and WQC2), as defined in Table 1. The data buffer was configured to cover a 45-h time history and was further divided into 15, 3-h intervals ($15 \times 3 \text{ h} = 45 \text{ h}$). For each 3-h interval, the algorithm calculated and stored the arithmetic mean and the variation, or number of fluctuation events occurring in the conductivity measurements. A fluctuation event was defined to occur when two consecutive conductivity measurements happened to differ by a value greater than a certain threshold value and was included to serve as an indicator of the variability in water quality experienced by the fish. The sensor was sampled every 60 s giving 180 conductivity measurements per interval. Each interval was then categorized into one of three different WQCs based on these two variables following the criteria shown in Table 1. At the time of acoustic transmission, the information in the buffer was further compressed into two 4-bit codes, each encoding the number of hours the fish

Table 1 Definition of water quality categories (WQCs)

| Water quality category | Range of conductivity average (μScm^{-1}) | Number of conductivity fluctuation events ($ \kappa_t - \kappa_{t-1} > 5 \mu\text{Scm}^{-1}$) | | Description |
|------------------------|--|--|----------|---|
| WQC0 | 0–25 | And | = 0 | Normal river water, main stem |
| WQC1 | 26–40 | And | < 4 | Stabilized river water during AI treatment |
| WQC2 | 0–25 | And | > 0 | River water with groundwater influence, or other atypical variations in conductivity, or brackish water (estuary) |
| | | Or | | |
| | 26–40 | And | ≥ 4 | |
| | | Or | | |
| > 40 | And | Any | | |

WQCs are based on certain combinations of average conductivity and the variation between consecutive conductivity measurements, or fluctuation events, over a 3-h interval containing a total of 180 measurements. A fluctuation event was defined to happen when conductivity changed by more than $5 \mu\text{Scm}^{-1}$ in 60 s

has spent in WQC0 and WQC1 over the last 45 h (see Fig. 1). Time spent in WQC2 was not transmitted explicitly but could be found implicitly by applying the formula $t_{\text{WQC2}} = 45 - (t_{\text{WQC0}} + t_{\text{WQC1}})$. Details of the tag encoding are shown in Fig. 1.

Following design, implementation and validation of the sensor tag prototype, a batch of 25 tags were manufactured by Thelma Biotel AS (Trondheim, Norway) for use in this study. The electronic tag that was designated as CondTag, had a cylindrical shape with 9 mm diameter and 43 mm length, weighed 6.3 g in air and 4.1 g in

freshwater, had an acoustic source level of 146 dB @1 m re. 1 μPa , and an estimated battery life of more than 90 days.

Tagging procedure

Adult Atlantic salmon ($N=6$, mean length 46.9 cm, SD 16.1 cm) and anadromous brown trout ($N=16$, mean length 48.4 cm, SD 14.9 cm) (Table 2) from river Lærdalselva, Norway (Fig. 2) were caught by angling using sports fishing equipment at several sites along the river. The species are both relevant as primary host (salmon)

Table 2 Length, species and tag-id for the marked fish

| Tag-id instant | Tag-id stat | Species | Length (cm) | Tagged | Tag site | First obs | Last obs |
|----------------|-------------|------------------------|-------------|--------|-----------------|-----------|----------|
| 69 | 70 | Anadromous brown trout | 35 | 15.08 | Oye | 16.08 | 17.09 |
| 75 | 76 | Anadromous brown trout | 35 | 07.08 | Rikheim | 19.08 | 22.09 |
| 77 | 78 | Anadromous brown trout | 43 | 06.08 | Rock | 16.08 | 06.09 |
| 81 | 82 | Anadromous brown trout | 33 | 06.08 | David (5.5) | 16.08 | 22.09 |
| 83 | 84 | Anadromous brown trout | 35 | 15.08 | Oye | 16.08 | 09.09 |
| 85 | 86 | Anadromous brown trout | 35 | 07.08 | Gronnebank | 16.08 | 30.08 |
| 91 | 91 | Anadromous brown trout | 43 | 06.08 | Rock | 29.08 | 19.09 |
| 93 | 94 | Anadromous brown trout | 52 | 07.08 | Rikheim | 24.08 | 22.09 |
| 95 | 96 | Anadromous brown trout | 54 | 06.08 | David (5.5) | 29.08 | 29.08 |
| 143 | 144 | Anadromous brown trout | 38 | 15.08 | Oye | 16.08 | 22.09 |
| 145 | 146 | Anadromous brown trout | 31 | 07.08 | Gronnebank | 16.08 | 21.09 |
| 147 | 148 | Anadromous brown trout | 57.5 | 07.08 | Per (5.3) | 06.09 | 19.09 |
| 151 | 152 | Anadromous brown trout | 48.5 | 06.08 | Rock | 16.08 | 16.08 |
| 155 | 156 | Anadromous brown trout | 41.5 | 06.08 | Per (5.3) | 28.08 | 17.09 |
| 73 | 74 | Atlantic Salmon | 48 | 15.08 | Rock | 25.08 | 06.09 |
| 79 | 80 | Atlantic Salmon | 84 | 06.08 | Robinson (15.7) | 02.09 | 05.09 |
| 87 | 88 | Atlantic Salmon | 55 | 14.08 | Grasmarki | 25.08 | 20.09 |
| 141 | 142 | Atlantic Salmon | 53 | 14.08 | Grasmarki | 16.08 | 15.09 |
| 149 | 150 | Atlantic Salmon | 84 | 07.08 | Sandebank (15) | 24.08 | 22.09 |

The first tag id refers to the instantaneous measurement (transmitter function i), the second tag id refers to the statistical data (transmitter function ii). The tag date, tag site and first/last observation is also given. For tagging locations not named on Fig. 2, the distance from the estuary is given in kilometres. The fish were not weighed during marking, but using observed weight of similar size fish from the same river we estimated the tag burden of the smallest fish to be < 1.4%. The tag weighs 4.1 g in water

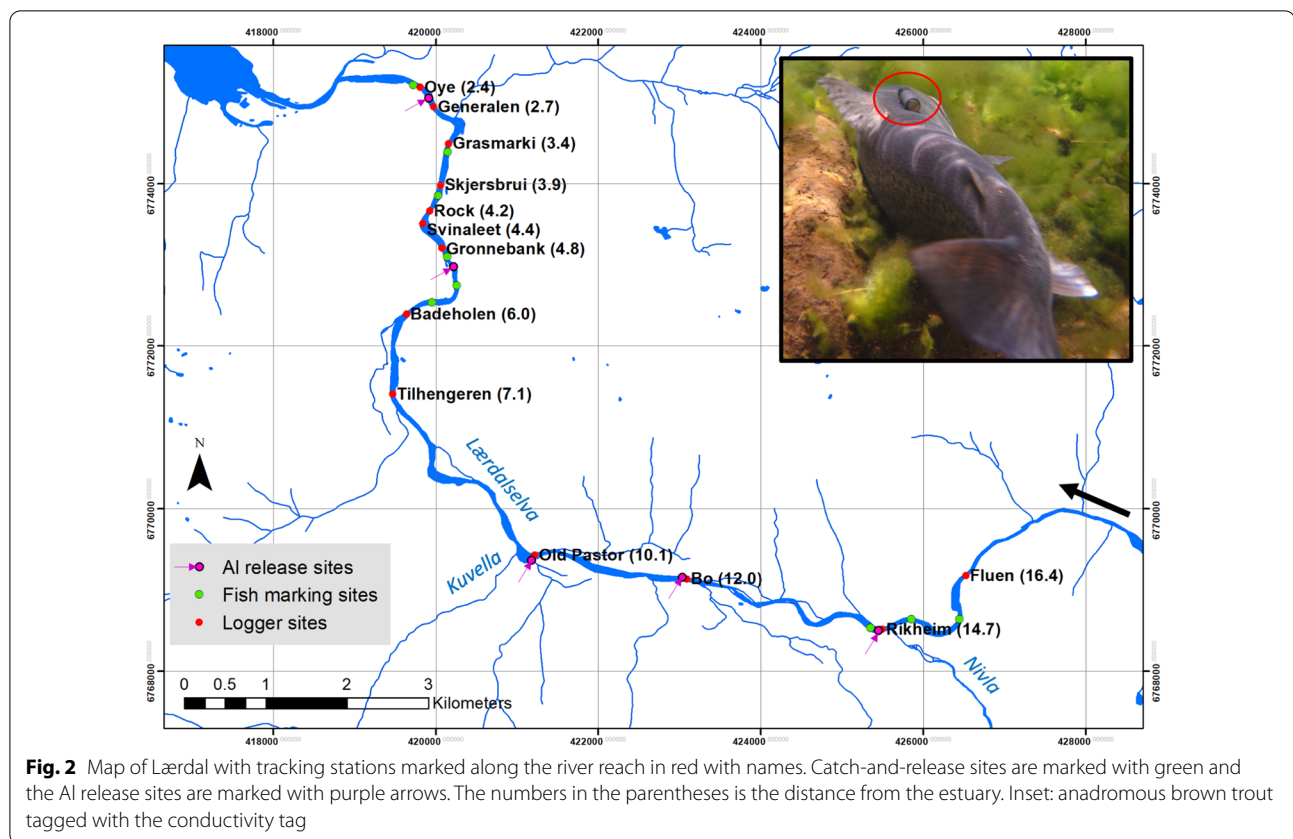


Fig. 2 Map of Lærdal with tracking stations marked along the river reach in red with names. Catch-and-release sites are marked with green and the AI release sites are marked with purple arrows. The numbers in the parentheses is the distance from the estuary. Inset: anadromous brown trout tagged with the conductivity tag

and long-term intermediate host (trout) for the parasite *G. salaris* [19].

After unhooking, fish were wet netted into a holding tank (volume 500 l) close to the riverbank. After 20–30 min, fishes were netted directly from the holding tank into a pre-anaesthetic sedation tank containing 0.5 mg l^{-1} metomidate for a minimum of 2 min. Fishes were then transferred to an anaesthetic bath containing 60 mg l^{-1} MS 222 (tricaine methanesulfonate) anaesthetic [20]. Cessation of response to peduncle pinching was used as a criterion for surgical anaesthesia. Fishes reached surgical anaesthesia within 4 min and were then transferred to a tank with river water where the tagging was conducted. During surgery the head, gills, and most of the body of each fish were submerged in water. Total handling time was around 2 min per fish. Immediately after tagging, the fish were transferred to a recovery tank with river water (80 l) with circulated flow and closely monitored. Fish regained balance ability and showed active swimming behaviour within 0.5–2 min of recovery. After a recovery period of 5–6 min, the fish were released into the river at the same site as it was angled. During recovery, tag readings were made and compared with data from a control tag permanently installed in the revival tank as well as manual conductivity and

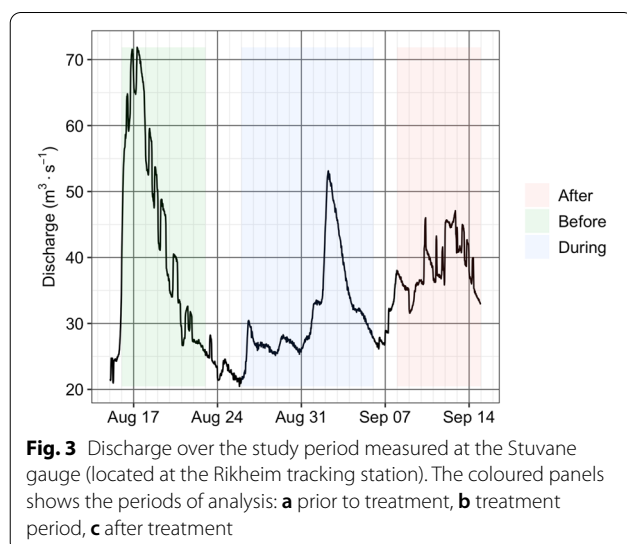
temperature measurements (WTW Multiparameter instrument). The tags were fitted with thin surgical steel wire and attached at two points just below the dorsal fin by leading the ends of the wire through the fish using 23 G ($0.60 \times 25 \text{ mm}$) syringes. The wire ends were secured on the opposite side by crimping on a small copper crimp with a 12-mm soft plastic disk as padding between the crimp and the fish's skin.

Tracking setup

The fish were followed by a stationary network of automatic listening receivers (VEMCO VR2W, locations shown in Fig. 2) and by daily manual tracking (first by manually deploying a VEMCO VR2W at each release location and later using a portable VEMCO VR100 directional hydrophone during August and September of 2009. Manual tracking was conducted in the river each day between the 14th of August and the 10th of September from 0800 to 2000 by following the same route. Manual tracking was also done on the 16th and 18th of September. This was done by walking upstream along the riverbank and placing both a passive receiver and the hydrophone of manual receiver into the river at different sections of the pools. In pools where fish were detected for more than 2 days, a passive receiver

was deployed. Once deployed in the river the passive receiver was at the same location during the whole study period. These passive receivers were offloaded daily to check if there had been registered movement of tagged fish during night-time.

The stationary receivers were mounted on the river bottom either using blocks of concrete or specially designed metal stands. Each site except Rikheim had one receiver and range tests were performed to ensure coverage of the entire river width. Lærdalselva is a relatively small river (widths 30–60 m) and all sites are easily accessed on the bank. The data from the stationary network and the manual tracking data were combined into a common dataset used in the analysis. For the analysis of the fish behaviour, three phases, before (defined from the 16th of August to the 23rd of August), during (defined from the 26th of August to the 6th of September), and after (defined from the 8th of September to the 15th of September) the Al treatment, were specified to get a consistent comparison of individual fish and to avoid effects of different time of release of the fish after tagging. A gap of 2 days is defined after the start of the treatment on the 24th of August to allow for the treatment to cover the entire river. Similarly, a gap of 1 day is defined between the period of treatment and the start of the after period to allow the treatment chemicals to be transported out of the system. The different phases of the study period are indicated in Fig. 3, which also shows the discharge in the reach during the treatment period. Data were also collected after the 15th of September to check movement and further ensure that fish were alive. For more information on the receiver network used in the experiment in river Lærdalselva, see Urke et al. [20].



Lærdalselva is a clearwater river and visual counting of salmonid spawners has been conducted from the early 1960s [21, 22]. The clear water made it possible to check the status of sensor/fish that had an observed fixed position in the river by snorkelling. One person drifting downstream by snorkelling and one person on the riverbank to register position and observations carried out this procedure. The surveys were conducted both in the upper part (Robinson–Rikheim) and in the lower part (Badehølen–Bruhølen). The diver observed natural behaviour in the fish encountered and fish with tags were seen. No dead fish were observed.

Other data

Two reference tags were placed at Bø and Øye together with the hydrophones. A continuous measurement of temperature was carried out during the experiment at the same locations by connecting a Vemco Minilog II to the hydrophone stand. Water quality was monitored manually during the treatment period. Discharge is measured at the Stuvane gauge (NVE station 73.2.0) with a time resolution of 30 min. Stuvane is located close to the Rikheim site (Fig. 2).

Aluminium treatment

Aluminium sulphate was added to all tributaries, as well as at several sites along the main river stem to obtain target concentrations all over the river system. In addition, the main river was acidified using sulphuric acid (30%) to bring pH down to effective treatment levels where Al is labile/cationic. Monitoring was done by using conductivity, pH and Al fractionation (Barnes–Driscoll). As the latter being very labour intensive, mainly the two former methods were used for direct control. The pH measurements were used as a feedback to the dosing stations and conductivity for daily dose control. Conductivity is not strongly related to discharge in this river system and is very low naturally. Monitoring stations upstream of the dosing sites confirmed the increase in conductivity during treatment, and the pre- and post-treatment measurements also confirm this quite consistently.

Statistical analysis

The relationship between movement and discharge was tested by computing the sum of movements for each half-hour interval that matched the discharge observations and then testing the number of movements against discharge and change in discharge using linear regression. A movement was counted when the fish was found in different locations in two consecutive observations. Conductivity data were checked for normality using qq-plots and histograms, and since the data were skewed, a Box Cox transformation was applied to the data using the package

EnvStats in R [23]. The changes in conductivity among the periods before, during and after treatment was then tested by first computing the averages for each fish for each period and then testing this using ANOVA across all periods and then a *t* test between periods, before–during, during–after and before–after. Furthermore, we

did a similar test on individual fish using ANOVA over all three periods and *t* tests on pairs of periods for each of the fish that had recordings over different periods. All analysis was done using the R software [24].

Results

To control the tag reading of temperature and conductivity, measurements were made in the recovery tank after surgery using a calibrated instrument (WTW multiparameter instrument). These were then compared to assess the accuracy of the tags. The recordings confirmed good correspondence between the measurement of temperature and conductivity from the tags and the instrument (Fig. 4, panel a shows temperature, panel b conductivity). This also confirmed that all tags were working at the time of release of the fish.

Of the 22 tagged fish, 19 were detected either by manual tracking or fixed receivers during the study period as indicated in Fig. 5. We find it most likely that the three fish found during the study period were located in areas with difficult acoustic conditions and therefore difficult to detect, but we cannot rule out mortality or tag malfunction. The fish could also have moved out of the study area. Twelve fish were recorded throughout the

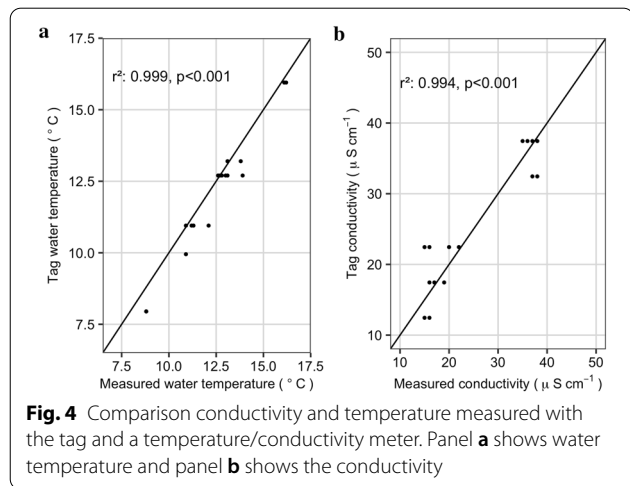


Fig. 4 Comparison conductivity and temperature measured with the tag and a temperature/conductivity meter. Panel a shows water temperature and panel b shows the conductivity

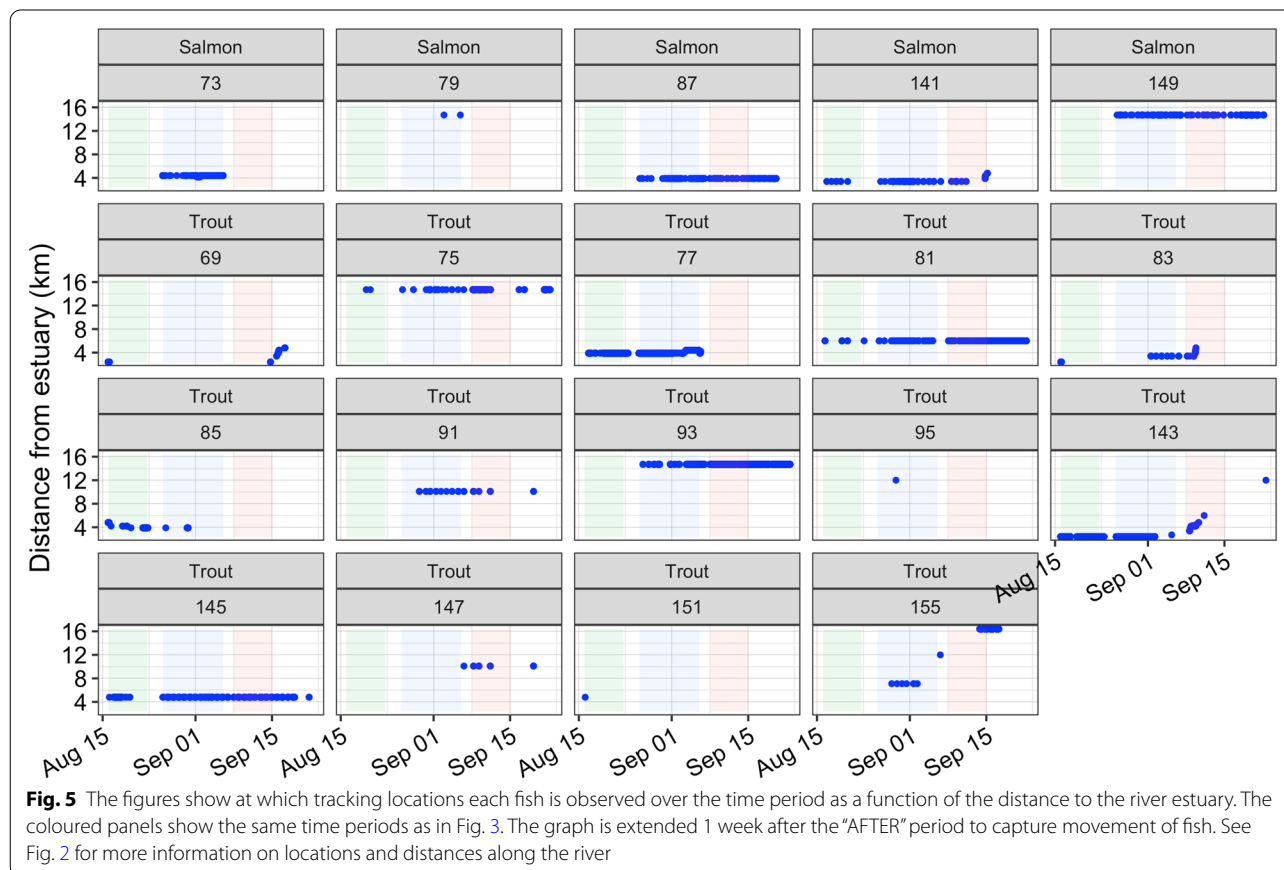


Fig. 5 The figures show at which tracking locations each fish is observed over the time period as a function of the distance to the river estuary. The coloured panels show the same time periods as in Fig. 3. The graph is extended 1 week after the “AFTER” period to capture movement of fish. See Fig. 2 for more information on locations and distances along the river

experimental period in relation to fixed receiver stations in the river, and the remainder were detected one or several times during the manual tracking campaigns. A total of 32,285 detections were made during the study period, distributed with 4454 before, 14,687 during, and 13,144 in the period after the treatment.

The position and movement of each individual fish are shown in Fig. 5, where the position of the fish is related to its distance from the river estuary. Relatively few movements were observed among the fish during the tracking period. From the data in Fig. 5, it is evident that only three fish out of 19 (16%, tags 73, 77 and 85) show downstream movements during the period. This occurred during treatment for two of the fish, but both of these fish returned to their original position after some time. The third fish moved 900 m downstream before the treatment started and stayed there. Five fish showed a distinct upstream movement during the study period (26%, tags 69, 83, 141, 143 and 155). All upstream movements took place after the treatment period, and the longest movement was 9.6 kms. The remainder of the tagged fish (58%) held position at one site during the entire period. The largest number of movements was observed in the period after the treatment, but no significant differences exist between the three periods. To check if discharge had an influence on movements, the number of movements was summed for each half-hour (resolution of the discharge times series) and linear regression between instantaneous discharge and the change of discharge were carried out. This shows no pattern connecting observed movement to the observed variability of discharge over the study period, movement vs. instantaneous discharge ($r^2 < 0.001$, $p > 0.05$) and movement vs. changes in discharge ($r^2 < 0.001$, $p > 0.05$). However, the observed rises and falls reside within normal variations in discharge and could not be considered as floods.

The average experienced conductivity of each fish based on the full set of telemetry data is shown in Fig. 6. There is a significant difference in conductivity experienced by the fish between the treatment periods (ANOVA, $F = 7.797$, $p < 0.01$). Looking at the different periods, we see a significant increase in conductivity between the period before treatment and the treatment period (t test, $t = -3.6623$, $p < 0.01$). We also see that the increase in conductivity observed in the telemetry data from the fish tags during the treatment period corresponds with an increase measured in the river for the same period. We do also see a significant reduction in conductivity between the treatment period and the period after (t test, $t = 3.0755$, $p < 0.01$). For the period before and period after treatment there are no significant difference in the conductivity experienced by the fish (t test, $t = -1.3099$, $p > 0.05$). For the full period, we see that the treatment

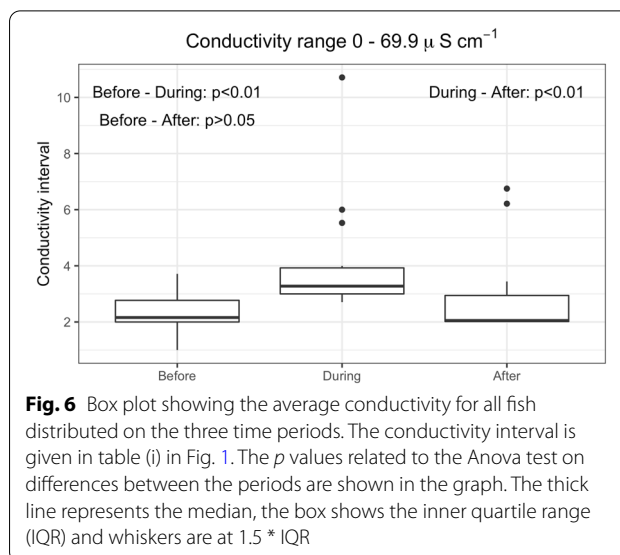
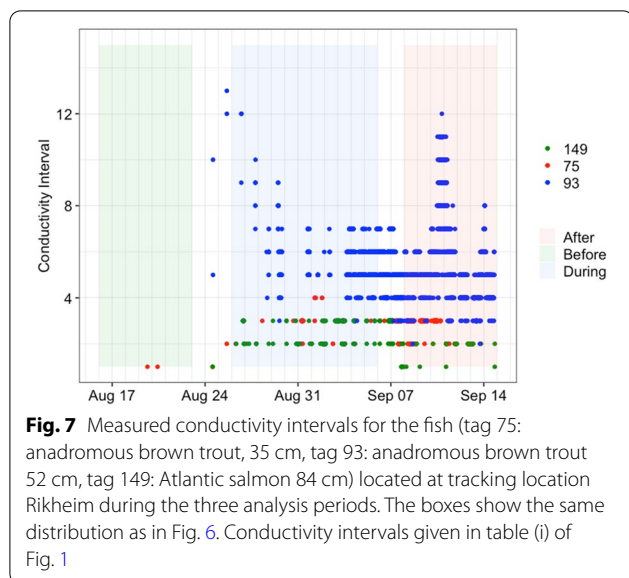


Fig. 6 Box plot showing the average conductivity for all fish distributed on the three time periods. The conductivity interval is given in table (i) in Fig. 1. The p values related to the Anova test on differences between the periods are shown in the graph. The thick line represents the median, the box shows the inner quartile range (IQR) and whiskers are at $1.5 * IQR$

raises the conductivity in the river followed by a reduction back to the level seen in the period before treatment when the treatment is over.

Further, an analysis of each individual fish between periods was carried out; see Fig. 5 for the periods where each tagged fish is observed. For the fish with observations in all three periods, an ANOVA test shows that there is a significant difference between the periods ($p < 0.001$). For fish with observations for the period before and during treatment, with one exception a t -test shows a significant increase in experienced conductivity for each individual fish during the treatment ($p < 0.001$ for all fish). The exception is an anadromous brown trout (tag 83) in the lower part of the river that shows only a slightly increase in median conductivity from before treatment to the treatment period. For fish recorded both in the treatment period and the period after treatment, we see a significant reduction in conductivity for all individuals ($p < 0.05$). When we compare the period before treatment to the period after treatment, the picture is mixed. Some fish are seen to return to the same level of conductivity as before the treatment, while for a few individuals we still see a significant difference in experienced conductivity.

As an example of observed conductivity in individual fish, Fig. 7 shows three fish (tags 75, 93 and 149) located at the Rikheim site 14.7 km from the estuary. These fish were present at this site for long periods during the study, and the results show individual variations that appear to be linked to the specific locations of the fish in the pool, which were determined by taking cross-bearings of the fish's ping pulses (transmitter function iii). The tributary Nivla enters the Rikheim site from the south, and this



stream discharge water of a natural higher conductivity level than the main river stem. The fish with tag 93 was located at the entrance of the tributary for most of the time and this shows up as a higher level of conductivity measured by the tag when compared to the other two fish which took other positions in the pool. A number of daily measurements at the Nivla outlet during the treatment period gave a median conductivity of $43 \mu\text{Scm}^{-1}$ (interval 7), and the median tag value gave $37.5 \mu\text{Scm}^{-1}$ (interval 6). The two other fish had a median value of $22.5 \mu\text{Scm}^{-1}$ (interval 3) during the treatment period.

The statistical function of the tag provided information on the time spent in different water quality categories (WQCs) over a 45-h sliding time window, as outlined in the section on tag design and Fig. 1. Figure 8 shows a situation where a fish (tag 81) intermittently came out of detection range and introduced significant gaps in the data received from this fish, but where the statistical recordings (transmitter function ii, Fig. 1) could be applied to evaluate the fish' continuous exposure to different water qualities irrespective of intermittent loss of contact. Each bar depicts a reception of a single statistical message and shows the fraction of time where the fish was exposed to WQC0 (normal river water—blue colour) or the combination of WQC1 and WQC2 (treatment/atypical water—red colour) of the preceding 45-h period. Instantaneous values are indicated as dots on top of the plot. Panel a shows the full dataset, while panel b details a subset of the data where the fish came out of detection range at two occasions and caused significant gaps in the recordings. The first gap lasted ~ 17 h, from the 1st of September 16:00 to the 2nd of September 09:00. It should be noted that this gap coincided with a distinct

rise in river discharge, which could be the reason for loss of reception either by the fish moving out to an area not covered by the receiver or a deterioration of the acoustic channel. When the fish was detected again on the 2nd of September, the first message reveals that the fish had been in stable and low conductivity water (WQC0) over the entire 45-h period preceding the reception of that message, including the 17 h when reception was lost. For the second gap, the fish was out of detection range for about 20 h, from the 2nd of September 14:30 to the 3rd of September 10:30. The first message received on the 3rd of September after the gap shows that the fish had sustained 6 h of exposure to water of elevated and/or fluctuating conductivity levels, and correspondingly a 39 h of exposure to normal river water over the last 45 h. Increasing exposure to elevated and/or more unstable levels of conductivity can be seen in the following hours, a tendency that continued towards the end of the treatment period and corresponded well with the change in general river water conductivity during the treatment. When the treatment ended, the tag reported an increasing prevalence of WQC0 (normal river water) with some lag due to the 45-h sliding window buffer, as should be expected.

Discussion

In this paper, we present the design of a multi-function acoustic sensor tag and the results from its practical use on adult Atlantic salmon and anadromous brown trout during a chemical AI treatment of the river Lærdalselva in Norway. Movements seen in the fish both during and after the treatment can be considered as natural migratory behaviour in Atlantic salmon and brown trout during this period of the year. The effect of the AI treatment on the fish' ambient water could be observed indirectly as an increased level of conductivity in the measurements received from the tagged fish. This demonstrates the utility of the sensor tag as a tool for in situ evaluation of the treatment process and it further confirms that the fish were exposed to the active reagent during the treatment. The main conclusion from the movement and conductivity data is therefore that the tagged fish showed no obvious signs of flight or avoidance behaviour upon exposure to the chemicals during the treatment. This is an important observation related to the effectiveness of the treatment.

In addition to sending regular instantaneous measurements on water conductivity and temperature, the tag was programmed to carry out an onboard analysis of an internally stored time history of conductivity measurements and report exposure times to different predefined categories of water quality. This function was implemented to prevent discontinuities and gaps in the received datasets due to anticipated limitations in

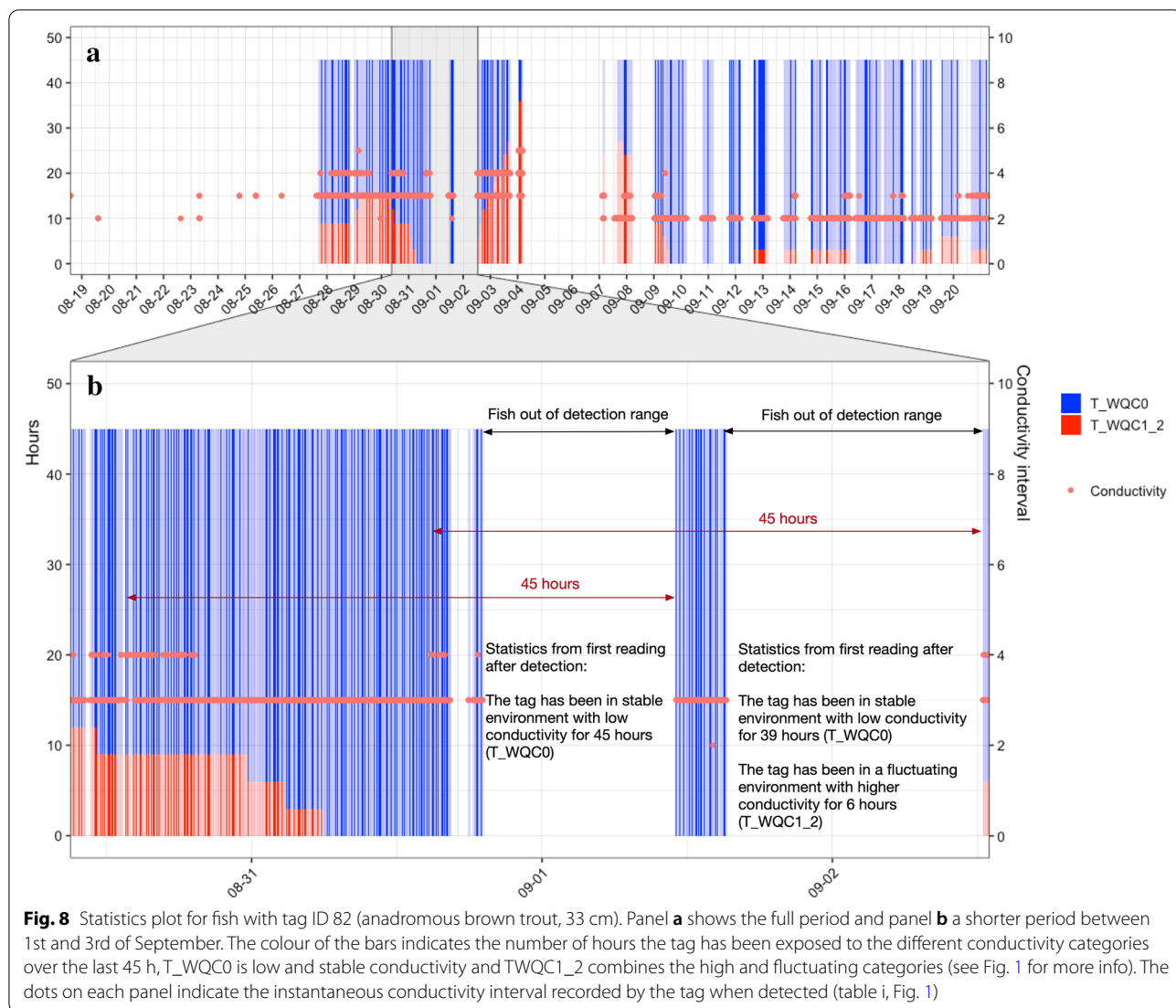


Fig. 8 Statistics plot for fish with tag ID 82 (anadromous brown trout, 33 cm). Panel **a** shows the full period and panel **b** a shorter period between 1st and 3rd of September. The colour of the bars indicates the number of hours the tag has been exposed to the different conductivity categories over the last 45 h, T_WQC0 is low and stable conductivity and TWQC1_2 combines the high and fluctuating categories (see Fig. 1 for more info). The dots on each panel indicate the instantaneous conductivity interval recorded by the tag when detected (table i, Fig. 1)

acoustic coverage and signal quality that are caused by the complex environment and turbulent conditions of a river. Given that the tag could be detected again within the time window spanned by its internal data buffer (45 h in this case), valuable aggregated information on the prevailing water quality conditions when the fish was beyond detection range would be secured. The utility of this function was clearly demonstrated in the case of an anadromous brown trout (tag 81) that was monitored at the site Badeholen throughout most of the study (Figs. 2 and 5), but was intermittently lost towards the end of the treatment period creating gaps in dataset of instantaneous conductivity measurements (Fig. 8). From the received data on exposure time to different water quality categories it was nevertheless possible to conclude that this fish had resided in what was categorized as normal river water (WQC0) during those intervals. However,

observations show that the fish was once again exposed to water affected by the reagents at the end of the treatment period. This observation corresponds well with measured conductivity just downstream of the fish location and where an incident in early September when high flow of water with low aluminium concentration from the tributary Kuvella led to a period of low concentration of Al_i in the main river, which was seen as a reduction in conductivity from $24 \mu S cm^{-1}$ to $20 \mu S cm^{-1}$ measured in the river just downstream of the fish location.

From a technical perspective, it should be noted that the statistical function was implemented without including any additional components like memories or computing power to the electronic tag platform. It was exclusively implemented by writing new firmware that exploited already existing hardware resources with only minor costs in battery life due to the extra processing

requirements. This demonstrates the flexibility and capacity provided by contemporary digital electronic fish tags to carry out on-board processing and analysis of sensor signals prior to transmission over the severely bandwidth-limited acoustic channel, a concept that has been utilized successfully in several subsequent telemetry studies [17, 25–27]. Even if the recorded sensor data must undergo substantial compression and loss of detail before acoustic transmission, the approach features an advantage over archival tags in that no recapture of the tag is needed to recover the data [25].

The tag also incorporated a concurrent acoustic “pinger” function in order to support manual localization and tracking of the fish with directional hydrophones. To avoid interference with the S256-encoded acoustic messages at 69 kHz, pings were emitted every 5 s on a separate frequency. This was shown to work as intended and proved to be a time-saving feature of considerable practical value during manual tracking campaigns where multiple pools and long stretches of the river had to be surveyed. The frequent pings provided rapid confirmation of the presence or absence of fish, which would not be the case if the much less frequent S256 signals (up to 2 min) had to be used for this purpose. The pinger function was also instrumental in determining the exact position of the anadromous brown trout (tag 93) at the Rikheim site which reported elevated conductivity levels compared with two other fish residing in the same pool (Fig. 7). Localization of the anadromous brown trout at the outlet of the tributary Nivla, which naturally sustains water of higher conductivity, warranted plausible explanation of the sensor readings and that the observation could not be attributed to the fish taking refuge in an unknown effluent of untreated water (e.g., groundwater), and thereby compromising the efficiency of the AI treatment.

In general, the acoustic receivers worked well in the stream environment, but turbulence in some areas made manual tracking time-consuming and required accurate positioning of the receiver to detect the transmissions. The simultaneous bankside tracking with the VR-100 and approaching the fish by snorkelling confirmed that fish transmitting a signal from the same location over a long period indeed were alive. A lower detection of fish tagged in the upstream part of the study site (from Rikheim and upstream) was observed during the experiment. Snorkelling confirmed that fish was alive, but heavy ripples and air entrainment made detection more difficult. No dead fish were observed in any of the snorkelling surveys.

One of the main challenges of the tag design presented in this study relates to the selection of appropriate parameters for processing and analyses, as well as achieving sufficient compression of the sensor data, which is

required to comply with the severely limited bandwidth of the acoustic telemetry link. The selection of parameters, such as conductivity and temperature bin sizes, averaging intervals and length of the sliding time window, threshold for conductivity fluctuation events, and specification of the different water quality categories (WQCs), all have direct impact on the relevance and quality of the data that may be harvested from the tags. Moreover, the parameters need to be selected prior to the actual study and depend on rather detailed a priori knowledge of the conditions that will prevail during the study. This information may not be fully available at the time of the tag design and programming, particularly if the study is novel and data background is sparse.

Efforts were made in this study to establish the configuration parameters as accurately as possible based on prior analyses of the water chemistry of the river Lærdalselva, both in its normal state and during earlier AI treatments [9]. However, in hindsight, several changes in the parameter selection could be envisioned in order to improve the performance of the tag. With the conductivity values experienced during this study, it would have been beneficial to select the conductivity intervals with a higher resolution in the lower ranges ($<40 \mu\text{S}/\text{cm}^{-1}$) at the expense of lower resolution in the higher ranges. No fish were observed to enter either the estuary or areas with water of high ionic strength such as groundwater effluents during the experiment, and the ability to detect such water qualities could in any case be limited to a couple of wide conductivity intervals above $40 \mu\text{S}/\text{cm}^{-1}$. Moreover, since temperature readings were of limited use in this study, a relocation of one or two bits from the temperature field to the conductivity field of the S256 code would double or quadruple the resolution of the conductivity intervals, respectively. This would undoubtedly make discrimination of normal river water from treatment water significantly clearer and such adjustments in the tag configuration parameters would be straightforward to implement in similar studies in the future.

Acoustic tags have been used in river environments both for Atlantic salmon smolts [20, 28, 29] and adults [30, 31], and provides a well-tested approach for tracking migratory fish in rivers [32]. Davidsen et al. [26] used a variation of the presented conductivity tag to track anadromous brown trout (*Salmo trutta*) during the CFT Legumin treatment of the river Vefsna to eradicate *G. salaris*. They found no avoidance behaviour and no survival, which indicate a successful rotenone treatment. Similar to the findings of Davidsen et al. [26], there were no avoidance behaviour in the Atlantic salmon and anadromous brown trout tagged in the study presented here, but in contrast no mortality was recorded which is an advantage of the AI treatment method. In another study,

Mitamura et al. [27] used a tag based on the design presented here to measure salinity during seaward migration of Atlantic salmon in a fjord in Norway. They utilized both the conventional tracking method and the storage feature of the tag to record the salinity, and found that the statistical data stored on the tag both provided a longer record of data and insight into fish using low salinity areas also in the outer fjord which would be difficult to obtain with a conventional tag and tracking setup.

As mentioned above, the data from the tagging experiment in river Lærdalselva show no obvious response in the fish during the release of Al and acid to remove *G. salaris*. This is important for the success of the procedure since only a few fish avoiding treatment could ensure the survival of the parasite and thereby reintroduce it to the fish population. A variation in the level of conductivity is observed in individual fish which indicate that they are exposed to different sources of water, which underline the importance of administering the treatment solution to tributaries and other areas where water influx is observed. During the study period all detected fish survived the experiment. This show that the Al treatment [5, 6] for *G. salaris* can be carried out without killing the host fish populations, which was a key factor in the development of the method. The operation to eradicate the parasite from Lærdal was ultimately considered a success since the control of fish in the river showed no parasite in the following years, and the river was declared free of *G. salaris* in the fall of 2017.

Conclusion

This paper describes the development of a multi-function acoustic transmitter tag equipped with sensors for in situ measurement of water quality in terms of conductivity and temperature. The tag transmits instantaneous measurements of water quality, while it also features onboard processing of measurement data to obtain statistical information on the fish's exposure to different water qualities over time. The latter function provides the means to evaluate the water quality experienced by the fish when it has been out of detection range. Simultaneously, the tag emits tracking signals (pings) on a separate frequency to facilitate efficient presence detection and fish localization. The tag was applied to provide data on the behaviour and water qualities experienced by Atlantic salmon and anadromous brown trout during an aluminium treatment aimed to eradicate the parasite *Gyrodactylus salaris* from the river Lærdal in Norway. The measurements obtained from the tagged fish show that the fish were exposed to aluminium during the treatment and that no evidence of avoidance behaviour was detected. The study provides an example of how experimental objectives may

be accommodated within the processing capabilities of contemporary digital acoustic tag platforms.

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Authors' contributions

AaG and JAA designed the acoustic tag based on specifications given by HAU and TK. HAU, TK, AGH and JAA designed the experiment. All authors participated in the field work. MK, KTA, JAA, HAU and TK performed data preparation and analysis. KTA wrote the manuscript with input from all other authors. All authors read and approved the final manuscript.

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Availability of data and materials

The datasets used and/or analysed during the current study are available from the corresponding author on reasonable request.

Ethics approval and consent to participate

Approval for the tagging experiment was granted by the Norwegian Animal Research Authority (ID 1292).

Consent for publication

Not applicable.

Competing interests

The authors declare that they have no competing interests.

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